Development, Improvements and Validation of a PV System Simulation Model in a Micro-Grid

Lucian Mihet-Popa^{*, **}, C. Koch-Ciobotaru^{**}, F. Isleifsson^{*} and H. Bindner^{*}

* Department of Electrical Engineering, Technical University of Denmark, 4000 Roskilde, Frederiksborgvej 399, Denmark Phone: (45) 2365 2984, E-Mail: lmih@elektro.dtu.dk, WWW: http://www.elektro.dtu.dk

** Department of Electrical Engineering, POLITEHNICA University of Timisoara, 300223 Timisoara, V. Parvan 2, Romania Phone: (40) 256-403464, E-Mail: lucian.mihet@et.upt.ro, WWW: http://www.et.upt.ro

<u>Abstract</u> – The increasing amount of Distributed Energy **Resources (DER) components into distribution networks** involves the development of accurate simulation models that take into account an increasing number of factors that influence the output power from the Distributed Generators (DG) systems. The modeling of DER components in power systems and the relative control architecture are an important part for the introduction of relevant quantity of renewable energy in the future smart grid. Therefore it is a strong necessity to have proper validated models to help operators to perform better studies and to be more confident with the results. This paper presents two simulation models developed and implemented in MATLAB/Simulink and DIgSILENT Power Factory of a PV system using the single-diode four-parameter model based on data sheet values. The component models were implemented first in MATLAB/Simulink and the simulation results have been compared with the data sheet values and with the characteristics of the units. To point out the strong dependency on ambient conditions and to validate the simulation models a complex data processing subsystem model has also been developed. A PV inverter model have also been developed and implemented in PowerFactory to study load flow, steady-state voltage stability and dynamic behavior of a distribution system. Validation of simulation models have been carried out using RISO experimental facility SYSLAB which include a PV System as well as a Vanadium Redox Flow Battery-VRB and various loads including an office building-FlexHouse in a LV network which can be operated in different configurations.

<u>Keywords:</u> Distributed Energy Resources, Distributed Generators, incident and tilt angle, Micro-Grid, PV panels, solar radiation.

I. INTRODUCTION

Renewable energy systems are expanding due to not only environmental aspect but also due to social, economical and political interest. The European Union is aiming at a specific CO_2 reduction in the electricity sector in the near future (20 % reduction by 2020). This will involve a significant growth of PV installation all over Europe resulting in a few hundred Giga watts of capacity [1-3].

The increased PV capacity will influence power system operation and design. Power supplied from a PV array depends mostly on present ambient conditions such as: irradiation and temperature [3-7].

The distributed generation is taking importance pointing out that the future utility line will be formed by distributed energy resources and micro-grids. The flexible micro-grid has to be able to import/export energy from/to the grid, control the active and reactive power flows and manage of the storage energy [3, 8].

PV output voltage changes mainly with temperature while PV output current changes mainly with irradiation. Therefore in order to develop a very precise simulation model the local wind speed and the solar radiation incidence angle, in terms of the slope and surface azimuth, should be considered [4-7, 9-11].

In order to determine the hourly incident radiation on a surface of any orientation it is necessary to evaluate the ratio of incident radiation on the tilted surface to that on a horizontal surface considering beam, sky diffuse and ground reflected radiation separately [4], [6], [9].

Increased distributed generation is becoming more important in the current power system and in the future it will rely more on distributed energy resources and microgrids. The flexible micro-grid has to be able to import/export energy from/to the grid, control the active and reactive power flows and manage of the storage energy [12-13].

This paper focuses on the simulation models of a smallscale PV System connected to a distributed network and on improvements and validating it using experimental facility of an active and distributed power systems laboratory. In order to find out the differences between DER components in power systems and to study the impact on bus voltage and frequency the system has been implemented in MATLAB/Simulink and PowerFactory.

II. DISTRIBUTED ENERGY SYSTEM ARCHITECTURE. EXPERIMENTAL FACILITY

SYSLAB is a laboratory for research in distributed control and smart grids with a high share of renewable energy production. Its experimental facility is a Wind/PV/Diesel Hybrid Mini-Grid with local storage and a novel control infrastructure [14]. The facility is spread across three sites located several hundred meters apart, as can be seen in Fig. 1a).

It includes two wind turbines (11kW and 55kW), a PVplant (7.8 kW), a diesel gen-set (48kW/60kVA), an intelligent office building with controllable loads (20kW), a number of loads (75kW, 3*36kW) and a Vanadium Battery of 15 kW/190 kWh. At each of the three sites there is a switchboard that allows the components installed at the site to be connected to either of two bus bars. The two bus bars at each site are connected to a crossbar switchboard allowing the flexible setup of the system(s) to be studied. The bus bars can be either connected to the national grid or can be part of an isolated system. It allows components and systems to be in grid connected operation, island operation, or operation in parallel with wind turbine or PV-plant, as it is shown in Fig. 1b).

The components are all connected in one distributed control and measurement system that enables very flexible setup with respect to experimental configuration.

A. PV Panels

The PV panels are mounted in three strings: two strings having 18 panels of 165 W each, and another one containing 12 panels of 100 W [15-18]. The strings are connected to the SYSLAB grid through a three-phase PV inverter (SMA Sunny Tripower [19]).



Fig. 1. a) SYSLAB Risø's new laboratory for intelligent, active and distributed power systems and b) details about SYSLAB Micro-Grid architecture.

From PV system two sets of data are provided. The first set consists of the ambient measurements from the weather station: solar irradiance on the horizontal, ambient temperature, and wind speed. The second set represents the electric measurements taken from the inverter: the AC output power to the grid, and on each PV string the DC power, voltage, and current. The two sets of data are read at different sampling frequencies: 1 Hz for the electrical and 0.1 Hz for the ambient. These large sets of data are used to develop an accurate model of the existing PV setup and to validate it.

B. Data Acquisition and Control System

The data acquisition and control system (hardware and software) is responsible for the supervision and control of the research platform for distributed intelligent energy systems with a high penetration of renewable energy. The supervisory software code was written in Java and is able to manage the data acquisition, processes the data and executes the control loop and outputs the control variables. The sensors outputs are connected to a signal conditioning board, which in turn is connected to the data acquisition (DAQ) board based on a PC (SCADA System).

III. PV PANELS and ARRAY MODELING

A. Modeling of the PV Panels

This paper uses a single diode equivalent circuit for the PV model, described by a simple exponential function [15-18]:

$$i = I_{sc} - I_0 \cdot \left(e^{(v+i \cdot R_s)/n_s \cdot V_T} - 1 \right)$$
(1)

In which I_{sc} and I_0 are the short-circuit and open-circuit currents, R_s is the cell series resistance, n_s is the number of cells in the panel connected in series and V_T represents the junction thermal voltage which includes the diode quality factor, the Boltzmann's constant, the temperature at standard test conditions (STC) and the charge of the electron.

Manufacturers typically provide limited operational data for photovoltaic panels. These data are available only at standard rating conditions, for which the irradiance G_a is 1000 W/m² and the cell temperature T_{cell} is 25 °C, except for the nominal operation conditions (NOCT) which is determined at 800 W/m² and an ambient temperature T_a of 20 °C.

Equations for the short circuit current I_{sc} and the open circuit voltage V_{oc} as a function of absolute temperature ΔT include temperature coefficients that provide the rate of change with respect to temperature of the PV performance parameters, can be express as [20-22]:

$$I_{sc} = I_{sc25} \cdot (1 + \beta_I \cdot \Delta T)$$

$$V_{oc} = V_{oc25} \cdot (1 + \chi \cdot \Delta T) \qquad (2)$$

$$\Delta T = T_{cell} - T_a$$

To complete the model it is also necessary to take into account the variation of the parameters with respect to irradiance [20-22]:

$$I_{sc} = I_{sc25} \cdot (G_a / 1000) \quad (3)$$

The model used to obtain the static characteristics of the PV panels has been developed in MATLAB using the equations presented above. The model was developed for one panel, as a function of irradiance and temperature. The model has as inputs G_a and T_{cell} on the panel and it sweeps the voltage range of the PV panel in order to calculate the output current and power. PV cells have nonlinear i-v and p-v characteristics. Its output voltage and power change according to temperature and irradiation [15-17].

Fig. 2 shows the typical characteristics for a PV model and also a comparison between PV technical characteristics of the Schuko S165-SP panel from datasheet (on the left) versus simulation results for the panel.

B. Modeling and Implementation of the PV Array

Using a four parameters model of a single diode equivalent circuit, the v-i characteristics for a solar panel string depending on irradiance and temperature has the following expressions:



$$i = n_{sp} \cdot I_{sc} \cdot \left(1 - e^{(\nu - n_{ps} \cdot V_{oc} + R_s \cdot i)/(n_{ps} \cdot n_s \cdot \nu)} \right)$$
(5)

The equations (4) and (5) were obtained replacing (2) and (3) in (1) and also introducing the number of panels in series (n_{ps}) for each string and the number of strings in parallel (n_{sp}) and can be used to calculate the voltage and current over a string of panels [20-22].

For obtaining the maximum power of the panel strings, the condition (dp/dv=0) should be fulfilled.

The block diagram implemented in Simulink that was developed to implement this model is depicted in Fig. 3.

IV. IMPROVEMENTS and VALIDATION of the PV ARRAY MODEL

A. Parameters dependence on operating conditions

Two types of measurements are taken from the experimental facility: ambient measurements from the weather station and electrical measurements taken from the inverter as can be seen in Fig. 4a). All these measurements are implemented into our model using a subsystem called *Measurements*, as it is shown in Fig. 4b).

The three ambient measurements: ambient temperature, horizontal solar radiation, and wind speed are fed to a module that calculates the cell temperature of the PV panels and the solar radiation on them.

The simulation model implemented in MATLAB/Simulink for a PV array with three strings is depicted in Fig. 4b). The irradiation, ambient temperature and wind speed are reading from a real data file measured by SCADA system as a function of time and then converted by Data processing subsystem in cell temperature and irradiation, parameters used as inputs to PV panels, as can also be seen in Fig. 4b).

1) Cell Temperature dependence

The cell temperature T_{cell} can be very different from the ambient temperature T_a and it depends on the solar irradiation G_a , T_a and also on the wind speed W_s . Solar irradiation acts on increasing T_{cell} and the wind speed has a cooling effect and lowers T_{cell} [4], [15-17].



Fig. 3. PV string model implemented in Simulink





Fig. 4. a) Description of the PV system model input values and b) the block diagram of the simulation model for PV array.

If the PV panels are mounted in the regions with high wind potential (as in our case) the wind speed must be considered. The forced (wind) convection is large for high wind speeds and the cell temperature function takes the following form [6]:

$$T_{cell} = T_a + \omega \cdot \left(0.32 / (8.91 + 2 \cdot W_s / 0.67)\right) \cdot G_a \quad (6)$$

Where ω is the mounting coefficient, which depends on the mounting conditions of the PV panels and *Ws* is the wind speed measured on horizontal plane.

The wind that produces the cooling effect through forced convection is the wind parallel to the panel surface; that is why the transformation $W_{sparallel} = W_s/0.67$ is used.

For a better understanding on the influence of solar irradiance and wind speed on the cell temperature, a graphical representation of these values is depicted in Fig. 5. The differences in temperature of the PV cells according to different considerations are also pointed out.



Fig. 5. Ambient measurements and their effect on the PV cell temperature.

2) Solar irradiance dependence

As can also be seen in Fig. 5 the solar irradiance has a high heating effect, at noon it can be seen around 50°C increase of cell temperature. Considering also the wind effect, the cell temperature is lowered, at noon, with 12°C. This change in temperature has an effect on the output power; as was shown in Fig. 2b). At each degree change in temperature, the efficiency modifies with approximately 0.44%: That means that if the temperature rises, the efficiency decreases and vice versa [20, 21].

The solar radiance has influence only on the current (Fig. 2c) and implicitly on the output power of the PV panel, so the plots contain the effect of the change in the input solar irradiance, according to the 'adaptation' of the horizontal solar irradiance to the real case of the PV panel, implemented in *Data processing* subsystem in Fig. 4b).

The solar irradiance input to the model (*Gcell*) is the horizontal value measured from the weather station. This translates into substantial differences as can also be seen in Fig 5 [15-17].

B. Validation of the Simulation Model

In order to validate the simulation model for the PV system, implemented in MATLAB/Simulink, and to point out the importance of considering the atmospheric conditions, such as irradiation, temperature and wind speed, and also the orientation and tilt angle of the panels, the simulations will be compared with experiments carried out using RISO experimental facility-SYSLAB.

In Fig. 6 are presented the simulation results versus measurements at different stages of the modeling. These Figures also shows the importance of several factors that have to be taken in consideration for obtaining a good accuracy of the simulation models.

In Fig. 6 a) is shown a comparison between measured and simulated output power of the panels (P_{DC}) for a time series of one day without considering wind speed effect or any improvements. As can be seen the difference between both curves is very big that means the simulation model should be improved to fit the measurement.

Fig. 6 b) shows the same waveforms for output power, with the same peak values, and the same changes in power due

to shading effect in a synchronous manner. The simulation has a delay of around 50 minutes. This is the effect of the PV panels' orientation, which have a 13° deviation from the E-W axis.

Considering the tilt angle and the orientation of the panels, the influence of solar irradiance and wind speed on the cell temperature the measurements and simulations are almost identically, as can be seen in Fig. 6 c).

In Fig. 7 are presented some simulation results versus measurements for Schuko165 PV panel installed at RISO campus. A good alignment between simulations and measurements was found, as can also be seen in Fig. 7.



Fig. 6. Simulation results versus measurements at different stages of the modeling.



Fig. 7. DC Current, Voltage and Power for Schuko165 PV panel and the output power of the inverter (P_{ac}) as a function of time for 24 hours.

V. SIMULATION MODEL of the PV SYSTEM DEVELOPED and IMPLEMENTED in POWERFACTORY for DISTRIBUTION NETWORKS

Computer models of power systems are widely used by power system utilities to study load flow, steady-state voltage stability and dynamic and transient behavior.

DIgSILENT PowerFactory has been chosen because provides the ability to simulate load flow, RMS fluctuations in the same software environment. It provides a comprehensive library of models for electrical components in the power system [23].

The dynamic model of the PV System implemented in PowerFactory has been built with standard components library and is based on the same equations used for MATLAB/Simulink model presented before.

The blocks of the PV model, DC-Link and controller of the Static Generator are implemented in the dynamic simulation language DSL of DIgSILENT. DSL allows the user to implement specific models that are not standard in the DIgSILENT library and thus to create own developed blocks either as modifications of existing models or as completely new models. The internal simulation language DSL has also been used to define the PV characteristics and to initialize the parameters and variables of the model.

Fig. 8 a) shows a single line diagram of the SYSLAB laboratory architecture implemented in PowerFactory [15-17].

Fig. 8 b) shows the schematic structure of the PV System model, developed for time-domain simulations where a DSL model is required, including Photovoltaic Model, DC-Link Model, PLL block and Static Generator with its Controller. The Static Generator is an easy to use model of any kind of static (non rotating) generators. The common characteristic of these generators is that they are all connected to the grid through a static converter. Applications are PV Generators, Storage devices, wind generators etc.

On the basic date tab of the single line diagram it is possible to set up the number of parallel generators and the power ratings of one PV panel.

For load flow analysis, also shown in Fig. 9, the local voltage controller could be set to three different modes: $\cos\varphi$, V and droop [23].

For RMS and EMT simulations the static generator supports two different models: controlled current and voltage source models. In our case we use a controlled current source model which has as inputs d-q axis reference current coming from the controller and d-q reference angles (*cosref* and *sinref*) from a PLL built-in model. Photovoltaic Model has as inputs irradiation G and cell temperature *tempCell*, obtained from MATLAB-Simulink model considering the tilt angle, orientation and the influence of solar irradiation and wind speed on the cell temperature (Fig. 4), implemented as a look-up table in our model. Also the MPP of current, power and voltage as a function of time for one module are shown.

In Fig. 10 is presented a comparison between measurements and simulations of the inverter output power for both PV modules (Schuko165 and SOLEL100) installed at RISO campus in three strings, two strings of 18 Schuko165 panels each and one string of 12 SOLEL panels





Fig. 8. a) Single line diagram of SYSLAB configuration implemented in PowerFactory and b) schematic block diagram of the PV system model.



Fig. 9. Simulation results of the PV system model implemented in PowerFactory.



Fig. 10. Comparison between simulations and measurements of the PV inverter output power for both types of panels (Sucho and Solel).

VI. CONCLUSIONS

This paper proposes a four-parameter model of a PV panel and a PV system, implemented in MATLAB/Simulink, using data provided by the manufacturer with semiempirical equations to predict the PV characteristics for any condition. PV characteristics are modeled according to a single diode four parameter equivalent circuit and PV parameters values taken from the manufacturer technical data. The paper also proposes a model that relies on ambient data from a local weather station, like most common in a real situation, not from sensors mounted on the PV panels. The model calculates the cell temperature and the solar irradiance on the PV panels considering, among others, the tilt angle, the orientation of the panels, and the wind cooling effect. The paper shows that these factors significantly influence the power output from the PV panels.

Comparison with experimental data, acquired by SCADA system and processed by MATLAB, and with the characteristics of the PV panels, provided by manufacturers, has shown that the model implemented in MATLAB/Simulink can be an accurate tool for the prediction of energy production.

A PV system model, using the same equations and parameters as in MATLAB/Simulink to define the PV module and characteristics, has also been developed and implemented in PowerFactory to study load flow, steadystate voltage stability and dynamic behavior of a distributed power system.

А comparison between both simulation models, implemented in MATLAB/Simulink and PowerFactory, has shown a good similarity. The models have also been validated against measurements using SYSLAB experimental facilities. That means that this work can be used for further development of tools for DER components in a distributed network.

APPENDIX

 TABLE 1. Data sheet parameters and values for PV panel
 [24]

Parameter (unit)	Value	Description
for STC – solar irradiance (G_a)=1000W/m ² , cell temperature(T_c)=25°C,		
wind speed 1m/s		
$P_{mpp}(W)$	165	Rated output power
$V_{mpp}(V)$	24.2	Nominal voltage
I _{mpp} (A)	6.83	Nominal current
$V_{oc25}(V)$	30.4	Open circuit voltage
Isc25 (A)	7.36	Short circuit current
α (%/°C)	-0.478	Temperature coefficient for change in
		(P _{mpp})
β (%/°C)	0.057	Temperature coefficient for change in
		(I _{sc})
χ (%/°C)	-0.346	Temperature coefficient for change in
		(U _{oc})
δ (%/°C)	-0.004	Temperature coefficient for change in
		(I _{mpp})
ε (%/°C)	50	Temperature coefficient for change in
		(U_{mpp})
for NOCT – solar irradiance(G_{aNOCT})=800W/m ² , ambient air		
temperature(T _{aNOCT})=20°C, wind speed 1m/s		
NOCT (°C)	46.2	Cell temperature on the above
		mentioned conditions

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